

# Tensor Methods for High-Dimensional Time Series Modeling

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May 10, 2022

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  - Motivation
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# Introduction



# High Dimensional Time Series

Big data is everywhere, and many big datasets are temporally dependent.

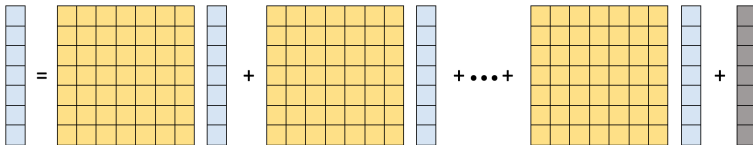
Needs for high-dimensional time series models:

- **Economics:** forecast with many predictors and understand causal relationships
- **Finance:** build large scale systemic risk models
- **Functional Genomics:** reconstruct gene regulatory networks based on limited experimental data
- **Neuroscience:** build detailed connectivity maps on temporal data exhibiting multiple structural changes

# Vector AutoRegression

- VAR is a fundamental model for multivariate time series analysis.
- VAR with  $N$  variables, lag order  $P$ , and time length  $T$ :

$$\mathbf{y}_t = \sum_{j=1}^P \mathbf{A}_j \mathbf{y}_{t-j} + \boldsymbol{\epsilon}_t, \quad \mathbf{y}_t = (y_{1t}, y_{2t}, \dots, y_{Nt})', \quad t = 1, \dots, T.$$



- This is called a VAR( $P$ ) model.
- **Curse of dimensionality** ( $N^2P \gg T$ ) even when the dimension  $N$  is moderately large.

# **Topic 1: High-Dimensional Vector Autoregression via Tensor Decomposition**

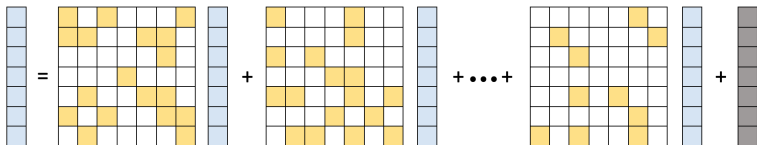
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## Motivation: Large Lag Order

- Compared with VAR, the vector autoregressive moving average (VARMA) model usually performs better in practice since it provides a more flexible autocorrelation structure.
- However, VARMA has a serious **identification** problem when  $N \geq 2$ . (Estimation is **unstable** since the objective function involves a high-order polynomial.)
- It is common to employ a VAR( $P$ ) model to approximate the VARMA process, and the lag order  $P$  may be very large to provide a better fit.
- As  $T \rightarrow \infty$ , we need  $P \rightarrow \infty$  and  $PT^{-1/3} \rightarrow 0$ .
- **Curse of dimensionality**

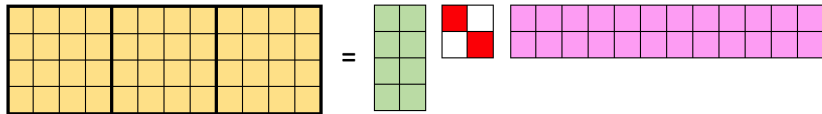
# Low-Dimensional Structures in VAR

- Sparse VAR model (Lasso, Dantzig selector, SCAD, etc.)



Basu and Michailidis (2015); Han et al. (2015); Wu and Wu (2016)

- Reduced-rank VAR model (SVD, nuclear norm)



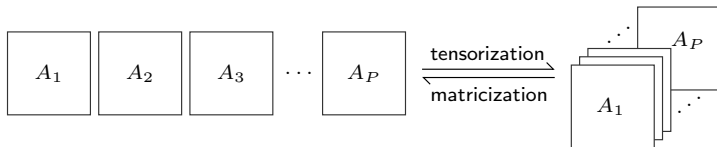
Velu et al. (1986); Negahban and Wainwright (2011); Chen et al. (2013)

Constraint on column space of  $[A_1, A_2, \dots, A_P]$ .



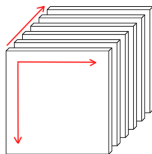
# VAR in Tensor Form

We propose to rearrange the transition matrices into a tensor



and consider dimensionality reduction in three different directions:

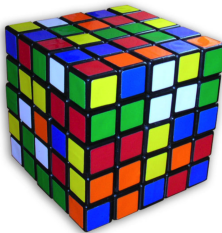
- column-wise  $[A_1, A_2, \dots, A_P]$  (reduced-rank model)
- row-wise  $[A'_1, A'_2, \dots, A'_P]$  (autoregressive index model)
- temporal  $[\text{vec}(A_1), \text{vec}(A_2), \dots, \text{vec}(A_P)]$  (new temporal structure)



# Vector, Matrix and Tensor

Tensors are higher-order extensions of matrices.

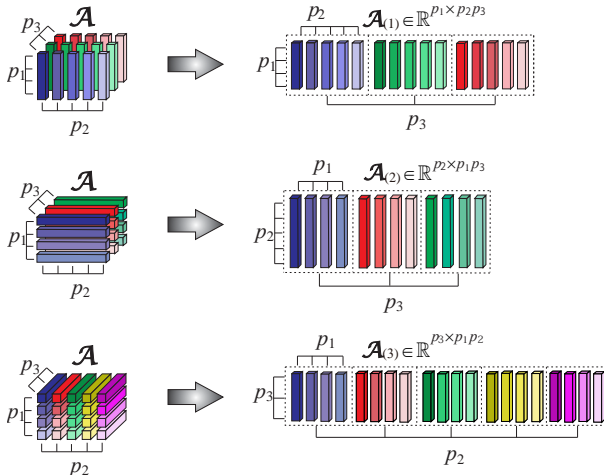
- 1st-order tensors are vectors ( $\mathbf{a}$ )
- 2nd-order tensors are matrices ( $\mathbf{A}$ )
- higher-order tensors ( $\mathcal{A}$ )



**Figure 1:**  $5 \times 5 \times 5$  tensor. This is a third-order tensor.

# Matricization and Tucker Ranks of a Tensor

Consider  $\mathcal{A} \in \mathbb{R}^{p_1 \times p_2 \times p_3}$ . For  $i = 1, 2, 3$ , its mode- $i$  matricization  $\mathcal{A}_{(i)}$  is



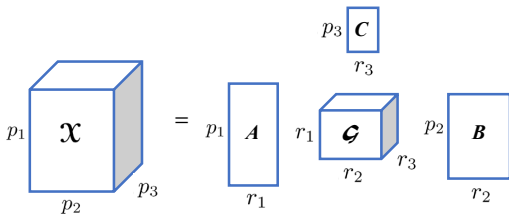
Let  $r_i = \text{rank}(\mathcal{A}_{(i)})$  be the matrix rank of  $\mathcal{A}_{(i)}$ .  $(r_1, r_2, r_3)$  are analogous to column and row ranks of a matrix, but they are not always equal.

# Tucker Decomposition

- For a tensor  $\mathcal{X} \in \mathbb{R}^{p_1 \times p_2 \times p_3}$ , the Tucker decomposition is

$$\mathcal{X} = \mathcal{G} \times_1 \mathbf{A} \times_2 \mathbf{B} \times_3 \mathbf{C} \equiv [\![\mathcal{G}; \mathbf{A}, \mathbf{B}, \mathbf{C}]\!]$$

where  $\mathcal{G}$  is a  $r_1 \times r_2 \times r_3$  core tensor,  $\mathbf{A}$  is a  $p_1 \times r_1$  matrix,  $\mathbf{B}$  is a  $p_2 \times r_2$  matrix, and  $\mathbf{C}$  is a  $p_3 \times r_3$  matrix.

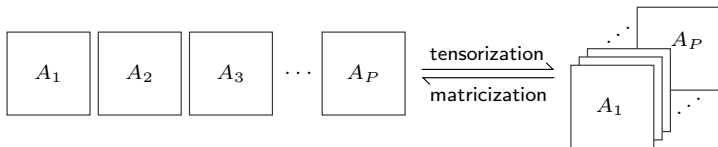


- Higher-order SVD:  $\mathcal{G}$  is all-orthogonal;  $\mathbf{A}$ ,  $\mathbf{B}$  and  $\mathbf{C}$  are orthonormal
- $(r_1, r_2, r_3)$ : Tucker ranks or multilinear ranks.

# Proposed Model: Multilinear Low-Rank VAR

- For a VAR( $P$ ) model, we stack  $A_1, \dots, A_P$  into an  $N \times N \times P$  tensor  $\mathcal{A}$ , where

$$\mathcal{A} = \mathcal{G} \times_1 U_1 \times_2 U_2 \times_3 U_3.$$



- If  $(r_1, r_2, r_3) \ll (N, N, P)$ ,

$$\# \text{ of parameters} = r_1 r_2 r_3 + r_1(N - r_1) + r_2(N - r_2) + r_3(P - r_3).$$

- The reduced-rank model is a special case of multilinear low-rank model with ranks  $(r, N, P)$ .

# Connection with the factor model

- Factor model:

$$\mathbf{y}_t = \mathbf{\Lambda} \mathbf{f}_t + \boldsymbol{\xi}_t, \quad (1)$$

where  $\mathbf{f}_t$  is a set of latent factor with dimension  $r \ll N$ ,  $\mathbf{\Lambda}$  is an  $N$ -by- $r$  factor loading matrix, and  $\boldsymbol{\xi}_t$  is the noise series.

- Estimated factor:  $\hat{\mathbf{f}}_t = \hat{\mathbf{\Lambda}}' \mathbf{y}_t$ .
- Supervised factor interpretation: since  $\mathbf{U}_i$  is orthonormal

$$\mathbf{U}_1' \mathbf{y}_t = \mathcal{G}_{(1)} \text{vec}(\mathbf{U}_2' \mathbf{X}_t \mathbf{U}_3) + \mathbf{U}_1' \boldsymbol{\epsilon}_t, \quad (2)$$

where  $\mathbf{X}_t = (\mathbf{y}_{t-1}, \dots, \mathbf{y}_{t-P})$ .

- $\mathbf{U}_1' \mathbf{y}_t$ :  $r_1$  response factors
- $\mathbf{U}_2' \mathbf{X}_t \mathbf{U}_3$ :  $r_2 \times r_3$  bilinear predictor factors.
- $r_1$ : response rank,  $r_2$ : predictor rank and  $r_3$ : temporal rank.

# Connection with VARMA

- The VARMA(1,1) process

$$\mathbf{y}_t = \Psi \mathbf{y}_{t-1} + \epsilon_t - \Theta \epsilon_{t-1} \quad (3)$$

has the VAR( $\infty$ ) form with  $\mathbf{A}_j = -\Theta^{j-1}(\Theta - \Psi)$  for  $j \geq 1$ :

$$\mathbf{y}_t = \epsilon_t + \mathbf{A}_1 \mathbf{y}_{t-1} + \mathbf{A}_2 \mathbf{y}_{t-2} + \mathbf{A}_3 \mathbf{y}_{t-3} + \cdots \quad (4)$$

Accordingly, we can define an  $N \times N \times \infty$  tensor  $\mathcal{A}_{\text{VARMA}}$ .

## Proposition 1

Under regularity conditions, if  $\text{rank}(\Theta) = r$  and  $\text{rank}(\Psi) = s$ , then  $\mathcal{A}_{\text{VARMA}}$  has multilinear ranks at most  $(r + s, r + s, r + 1)$ .

- VAR( $P$ ) approximation is easier to implement but involves more parameters.
- Tucker decomposition reduces the dimensionality and alleviates the overparametrization.

# Multilinear Low-Rank Estimator

- Denote  $\mathbf{x}_t = (\mathbf{y}'_{t-1}, \dots, \mathbf{y}'_{t-P})'$ . Given Tucker ranks  $(r_1, r_2, r_3)$ , consider the multilinear low-rank (MLR) estimator

$$\begin{aligned}\hat{\mathcal{A}}_{\text{MLR}} &\equiv [\hat{\mathcal{G}}; \hat{\mathbf{U}}_1, \hat{\mathbf{U}}_2, \hat{\mathbf{U}}_3] \\ &= \arg \min \sum_{t=1}^T \|\mathbf{y}_t - (\mathcal{G} \times_1 \mathbf{U}_1 \times_2 \mathbf{U}_2 \times_3 \mathbf{U}_3)_{(1)} \mathbf{x}_t\|_2^2.\end{aligned}$$

- Alternating least squares algorithm:
  - Update  $\mathcal{G}$ ,  $\mathbf{U}_1$ ,  $\mathbf{U}_2$ ,  $\mathbf{U}_3$  alternately.
  - Each step is an OLS problem.

## Theorem 1 (Asymptotic Normality)

Under regularity conditions, if  $N$  and  $P$  are fixed, then as  $T \rightarrow \infty$ ,

$$\sqrt{T}(\text{vec}(\hat{\mathcal{A}}_{\text{MLR}}) - \text{vec}(\mathcal{A})) \xrightarrow{d} N(0, \boldsymbol{\Sigma}_{\text{MLR}}).$$



# Rank Selection

- We propose a ridge-type ratio estimator to determine  $(r_1, r_2, r_3)$ .
- Based on an initial estimator  $\hat{\mathcal{A}}$  (e.g., the OLS estimator or the nuclear norm estimator), we estimate  $(r_1, r_2, r_3)$  by

$$\hat{r}_i = \arg \min_{1 \leq j \leq p_i - 1} \frac{\sigma_{j+1}(\hat{\mathcal{A}}_{(i)}) + c}{\sigma_j(\hat{\mathcal{A}}_{(i)}) + c}, \quad 1 \leq i \leq 3,$$

where  $p_1 = p_2 = N$ ,  $p_3 = P$ , and  $c$  is a well-chosen parameter.

## Theorem 2 (Rank Selection Consistency)

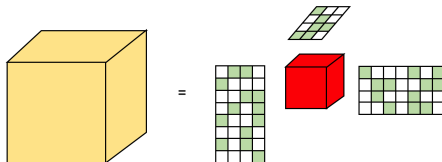
Under the conditions of Theorem 1, if  $c$  is chosen such that

$T^{-1/2} \ll c \ll \sigma_{r_i}(\mathcal{A}_{(i)}) \cdot \min_{1 \leq j < r_i} \sigma_{j+1}(\mathcal{A}_{(i)})/\sigma_j(\mathcal{A}_{(i)})$ , for  $1 \leq i \leq 3$ ,

$$\mathbb{P}(\hat{r}_1 = r_1, \hat{r}_2 = r_2, \hat{r}_3 = r_3) \rightarrow 1, \quad \text{as } T \rightarrow \infty.$$

# SHORR Estimator

- Sparsity in  $\mathbf{U}_i \Rightarrow$  variable selection in factor loadings



- Sparse Higher-Order Reduced Rank (SHORR) estimator:

$$\begin{aligned}\hat{\mathcal{A}}_{\text{SHORR}} &\equiv [\hat{\mathcal{G}}; \hat{\mathbf{U}}_1, \hat{\mathbf{U}}_2, \hat{\mathbf{U}}_3] \\ &= \arg \min \left\{ \frac{1}{T} \sum_{t=1}^T \|\mathbf{y}_t - (\mathcal{G} \times_1 \mathbf{U}_1 \times_2 \mathbf{U}_2 \times_3 \mathbf{U}_3)_{(1)} \mathbf{x}_t\|^2 + \lambda \|\mathbf{U}_3 \otimes \mathbf{U}_2 \otimes \mathbf{U}_1\|_1 \right\}\end{aligned}$$

subject to  $\mathcal{G}$  is all-orthogonal and  $\mathbf{U}_i$  is orthonormal, where  $\|\cdot\|_1 = \|\text{vec}(\cdot)\|_1$  for matrices.

- $\|\mathbf{U}_3 \otimes \mathbf{U}_2 \otimes \mathbf{U}_1\|_1$  induces sparsity for three factor matrices jointly.

# SHORR Estimator

- We propose an alternating direction method of multipliers (ADMM) algorithm.
- Nonasymptotic error bounds:

## Theorem 3 (Simplified by assuming $(r_1, r_2, r_3)$ are fixed)

Under regularity conditions, if  $\lambda \gtrsim \sqrt{\log(N^2 P)/T}$  and  $T \gtrsim \log(N^2 P)$ , then with high probability,

$$\|\hat{\mathcal{A}}_{\text{SHORR}} - \mathcal{A}\|_{\text{F}} \lesssim \sqrt{s_1 s_2 s_3} \lambda,$$

$$\frac{1}{T} \sum_{t=1}^T \|(\hat{\mathcal{A}}_{\text{SHORR}} - \mathcal{A})_{(1)} \mathbf{x}_t\|_2^2 \lesssim \tau^2 s_1 s_2 s_3 \lambda^2,$$

where  $s_i$  is the maximum number of nonzero entries in each column of  $U_i$ , for  $1 \leq i \leq 3$ .

- Estimation convergence rate is  $\sqrt{s_1 s_2 s_3 \log(N^2 P)/T}$ .

# Comparison of Estimation Efficiency

Estimator	Structure	Estimation error rate
SHORR	low-rank & sparsity	$\sqrt{s_1 s_2 s_3 \log(N^2 P)/T}$
Lasso	sparsity	$\sqrt{\ \mathcal{A}\ _0 \log(N^2 P)/T}$
Nuclear	low-rank	$\sqrt{rNP/T}$

Introducing **sparsity** into the **low-rank** decomposition can improve the estimation efficiency.

# Macroeconomic Forecasting

- A list of 40 major U.S. quarterly macroeconomic variables from Q1-1959 to Q4-2007, seasonally adjusted and transformed to be stationary. Eight categories:

- |                                     |                  |
|-------------------------------------|------------------|
| (1) GDP and its decomposition       | (2) NAPM indices |
| (3) industrial production           | (4) housing      |
| (5) money, credit and interest rate | (6) employment   |
| (7) prices and wages                | (8) others       |

- Apply VAR(4) model. Select  $(r_1, r_2, r_3) = (4, 3, 2)$ .
- Perform rolling forecast from Q4-2000 to Q4-2006. Forecast error:

Criterion	Non-regularized methods				Regularized methods				
	OLS	RRR	DFM	MLR	SHORR	LASSO	RSSVD	NN	SOFAR
$\ell_2$ norm	20.16	13.31	6.36	<b>5.81</b>	<b>5.35</b>	6.72	6.33	8.16	6.28
$\ell_\infty$ norm	8.32	4.55	2.85	<b>2.56</b>	<b>2.44</b>	3.06	3.02	3.36	3.02

- SHORR and MLR have impressive forecasting accuracy compared to competing methods.

### Response factors $U_1$

- Almost all variables are selected.
- Each factor covers multiple categories of macroeconomic indices.
- No group structure can be observed.

-0.195	0.195	0.008	
	0.465	0.023	0.001
	0.351		
-0.297			-0.034
-0.063	-0.172		
-0.298	-0.114		-0.076
		0.028	
-0.094	0.368	0.020	
	-0.059		0.413
-0.029	-0.207		0.425
-0.249			0.183
-0.320		-0.026	
	-0.109		0.473
-0.363			
-0.302			
-0.004	0.071	0.785	0.178
0.049	0.347	-0.424	0.459
-0.086			
-0.077			-0.035
0.097	0.107		
0.087			
	0.131		-0.162
-0.123			0.082
-0.016			
-0.126	-0.077	-0.383	-0.202
-0.269		0.132	0.046
-0.278			
0.002	0.346		-0.016
-0.228	0.120		
0.331			
	0.267	0.145	
-0.068			
			0.025
	0.005		0.018
	-0.037	-0.105	0.218
-0.076	-0.146		
		0.082	-0.082
	0.008		-0.106

### Response Factors

Short Name

GDP251		-0.310	0.155
GDP252			-0.012
GDP253			0.014
GDP256	-0.014	0.332	-0.118
GDP263			
GDP264			
GDP265			
GDP270			
PMCP	0.065		
PMDEL	0.172		
PMI	-0.021	-0.870	0.006
PMNO	0.761	-0.020	
PMNV			
PMP	-0.621		
IPS10			
UTL11		-0.007	0.849
HSFR		-0.196	-0.494
BUSLOANS			
CCINRV			
FM1			
FM2			
FMRNBA			
FMRRA			
FSPIN			
FYFF			
FYGT10			
SEYGT10	-0.069		
CES002			
LBMNU			
LBOUT			
LHEL			
LHUR			
CES275R			
CPIAUCSL			
GDP273			
GDP276			
PSCCOMR			
PWFS			
EXRUS			
HHSNTN			

### Predictor Factors

Predictor factors  $U_2$

- Only 12 variables are selected, all but one from the first four categories.
- Activeness of production and investment serves as the driving force of the whole economy.

Category
GDP Decomposition
NAPM Indices
Industrial Production
Housing
Money, Credit, Interest Rate
Employment
Prices and Wages
Others

0.8
0.6
0.4
0.2
0
-0.2
-0.4
-0.6
-0.8

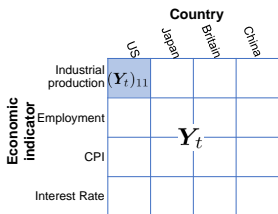
### Legend

## Topic 2: Low-Rank Tensor Autoregression

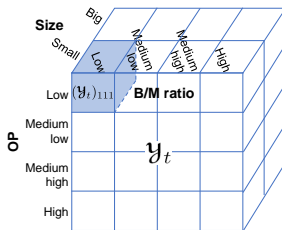
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# Tensor-Value Time Series Data

- Tensor-valued time series can be found in many fields: economics, portfolio analysis, neuroscience, bioinformatics, computer vision, ...
- Denoted by  $\{\mathbf{y}_t, t = 1, \dots, T\}$ , where  $\mathbf{y}_t \in \mathbb{R}^{p_1 \times \dots \times p_d}$ . When  $d = 1$ , vector-valued time series  $\{\mathbf{y}_t\}$ . When  $d = 2$ , matrix-valued time series  $\{\mathbf{Y}_t\}$ .



(a) Matrix-valued  $\mathbf{Y}_t \in \mathbb{R}^{4 \times 4}$



(b) Tensor-valued  $\mathbf{y}_t \in \mathbb{R}^{4 \times 4 \times 2}$

**Figure 2:** Observation at time  $t$  for (a) a  $4 \times 4$  matrix-valued macroeconomic indicators time series  $\{\mathbf{Y}_t\}$  and (b) a  $4 \times 4 \times 2$  tensor-valued stock portfolio returns time series  $\{\mathbf{y}_t\}$ . OP: operating profitability; B/M: book-to-market.



# How to model tensor-valued time series?

- Consider  $\mathbf{y}_t \in \mathbb{R}^{4 \times 4 \times 2}$  in Figure 1(b). A simple approach is the VAR:

$$\text{vec}(\mathbf{y}_t) = \mathbf{A} \text{vec}(\mathbf{y}_{t-1}) + \text{vec}(\boldsymbol{\varepsilon}_t), \quad (5)$$

where  $\mathbf{A} \in \mathbb{R}^{32 \times 32}$  is the unknown transition matrix. It can incorporate linear associations between every variable in  $\mathbf{y}_t$  and that in  $\mathbf{y}_{t-1}$ .

- Even with only one lag, # of parameters =  $32^2 = 1024$ . (curse of dimensionality)
- The vectorization will destroy the intrinsic **multidimensional** structural information of the observed tensors  $\mathbf{y}_t$ . (lack of interpretability)

# Multi-Mode Matricization

- For a fixed index set  $S \subset \{1, 2, \dots, d\}$ , the **multi-mode matricization** of  $\mathcal{X} \in \mathbb{R}^{p_1 \times \dots \times p_d}$  is the matrix

$$\mathcal{X}_{[S]} \in \mathbb{R}^{\prod_{i \in S} p_i \times \prod_{i \notin S} p_i},$$

with  $\prod_{i \in S} p_i$  rows and  $\prod_{i \notin S} p_i$  columns<sup>a</sup>.

- One-mode matriciation:** The mode- $i$  matricization of  $\mathcal{X}$ ,  $\mathcal{X}_{(i)}$ , is simply  $\mathcal{X}_{[\{i\}]}$ .

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<sup>a</sup>Specifically, its  $(i, j)$ -th entry is

$$(\mathcal{X}_{[S]})_{i,j} = \mathcal{X}_{i_1, \dots, i_d},$$

where  $i = 1 + \sum_{k \in S} (i_k - 1)I_k$  and  $j = 1 + \sum_{k \notin S} (i_k - 1)J_k$ , with  $I_k = \prod_{\ell \in S, \ell < k} p_\ell$ , and  $J_k = \prod_{\ell \notin S, \ell < k} p_\ell$ .

# Proposed Model: Low-Rank Tensor Autoregression (LRTAR)

We propose

$$\mathbf{y}_t = \langle \mathcal{A}, \mathbf{y}_{t-1} \rangle + \boldsymbol{\varepsilon}_t,$$

where

$$\mathbf{y}_t, \boldsymbol{\varepsilon}_t \in \mathbb{R}^{p_1 \times \cdots \times p_d},$$

and

$$\mathcal{A} \in \mathbb{R}^{p_1 \times \cdots \times p_d \times p_1 \times \cdots \times p_d}$$

is a  $2d$ -th-order transition tensor with Tucker ranks  $(r_1, \dots, r_{2d})$ , i.e.,

$$r_i = \text{rank}(\mathcal{A}_{(i)}), \quad i = 1, \dots, 2d.$$

# Tucker Decomposition and Connection with VAR

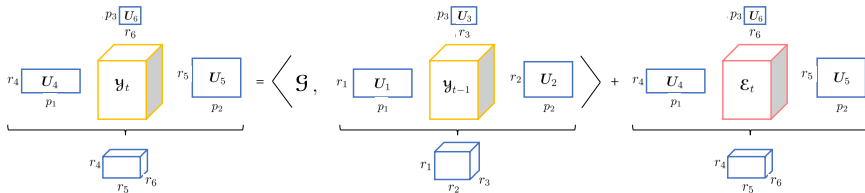
- $\mathcal{A}$  has the Tucker decomposition  $\mathcal{A} = \mathcal{G} \times_{i=1}^{2d} \mathbf{U}_i$ , with core tensor  $\mathcal{G} \in \mathbb{R}^{r_1 \times \dots \times r_{2d}}$  and factor matrices  $\mathbf{U}_i \in \mathbb{R}^{p_i \times r_i}$ ,  $1 \leq i \leq 2d$ .
- Define index sets  $S_1 = \{1, 2, \dots, d\}$  and  $S_2 = \{d+1, d+2, \dots, 2d\}$ . Then the LRTAR can be written in the VAR form:

$$\text{vec}(\mathbf{y}_t) = \overbrace{(\otimes_{i \in S_2} \mathbf{U}_i) \mathcal{G}_{[S_2]} (\otimes_{i \in S_1} \mathbf{U}_i)^\top}^{\mathcal{A}_{[S_2]}} \text{vec}(\mathbf{y}_{t-1}) + \text{vec}(\mathcal{E}_t)$$

- The transition matrix is the multi-mode matricization of  $\mathcal{A}$ ,  $\mathcal{A}_{[S_2]} \in \mathbb{R}^{\prod_{i=1}^d p_i \times \prod_{i=1}^d p_i}$ .
- # of parameters is reduced from  $(\prod_{i=1}^d p_i)^2$  dramatically to

$$\prod_{i=1}^{2d} r_i + \sum_{i=1}^d r_i(p_i - r_i) + \sum_{i=1}^d r_{d+i}(p_i - r_{d+i}).$$

# Dynamic Tensor Factors Interpretation



**Figure 3:** Low-dimensional dynamic factor structure when  $\mathbf{y}_t$  is a third-order tensor.

- Consider the HOSVD: all  $\mathbf{U}_i$  are orthonormal. Then the LRTAR implies a low-dimensional tensor regression:

$$\underbrace{\mathbf{y}_t \times_{i=d+1}^{2d} \mathbf{U}_i^\top}_{r_{d+1} \times r_{d+2} \times \cdots \times r_{2d}} = \langle \mathcal{G}, \underbrace{\mathbf{y}_{t-1} \times_{i=1}^d \mathbf{U}_i^\top}_{r_1 \times r_2 \times \cdots \times r_d} \rangle + \mathcal{E}_t \times_{i=d+1}^{2d} \mathbf{U}_i^\top,$$

- $\mathbf{y}_t \times_{i=d+1}^{2d} \mathbf{U}_i^\top$ :  $r_{d+1} \times r_{d+2} \times \cdots \times r_{2d}$  response factors
- $\mathbf{y}_{t-1} \times_{i=1}^d \mathbf{U}_i^\top$ :  $r_1 \times r_2 \times \cdots \times r_d$  predictor factors

# Regularization via Square Matricizations

- $\mathcal{A}$  is a  $p_1 \times \cdots \times p_d \times p_1 \times \cdots \times p_d$  tensor. The multi-mode matricization  $\mathcal{A}_{[I]}$  will be a  $\prod_{i=1}^d p_i \times \prod_{i=1}^d p_i$  square matrix if the index set is

$$I = \{\ell_1, \dots, \ell_d\}, \quad \text{where } \ell_i \in \{i, d+i\} \quad \text{for } i = 1, \dots, d.$$

- There are totally  $2^d$  square matricizations of  $\mathcal{A}$ , denoted by  $\mathcal{A}_{[I_k]}$  with  $1 \leq k \leq 2^d$ . Note that  $\text{rank}(\mathcal{A}_{[I_k]}) \leq \min(\prod_{i=1, i \in I_k}^{2d} r_i, \prod_{i=1, i \notin I_k}^{2d} r_i)$ .
- To simultaneously encourage low-rankness across all square matricizations, and hence across all modes, we propose a novel regularizer based on the **Sum of Square-matrix Nuclear (SSN) norm**:

$$\|\mathcal{A}\|_{\text{SSN}} = \sum_{k=1}^{2^d} \|\mathcal{A}_{[I_k]}\|_*,$$

where  $\|\mathbf{X}\|_* = \sum_j \sigma_j(\mathbf{X})$  is the nuclear norm, with  $\sigma_j(\mathbf{X})$  being the  $j$ -th largest singular value of  $\mathbf{X}$ .

# SSN Norm Regularized Estimator

- We propose the SSN norm regularized estimator

$$\hat{\mathcal{A}}_{\text{SSN}} = \arg \min_{\mathcal{A}} \left\{ \frac{1}{T} \sum_{t=1}^T \|\mathbf{y}_t - \langle \mathcal{A}, \mathbf{y}_{t-1} \rangle\|_{\text{F}}^2 + \lambda_{\text{SSN}} \|\mathcal{A}\|_{\text{SSN}} \right\}.$$

## Theorem 4

Under regularity conditions, if  $\lambda_{\text{SSN}} \gtrsim 2^{-d} \sqrt{p/T}$ , and  $T \gtrsim p$ , then with high probability,

$$\begin{aligned} \|\hat{\mathcal{A}}_{\text{SSN}} - \mathcal{A}\|_{\text{F}} &\lesssim \sqrt{s}(2^d \lambda_{\text{SSN}}), \\ T^{-1} \sum_{t=1}^T \|\langle \hat{\mathcal{A}}_{\text{SSN}} - \mathcal{A}, \mathbf{y}_{t-1} \rangle\|_{\text{F}}^2 &\lesssim C s (2^d \lambda_{\text{SSN}})^2, \end{aligned}$$

where  $p = \prod_{i=1}^d p_i$  and  $\sqrt{s} = 2^{-d} \sum_{k=1}^{2^d} \sqrt{2s_k}$ , with  $s_k = \text{rank}(\mathcal{A}_{[I_k]})$ .

- Estimation convergence rate is  $2^{-d} \sum_{k=1}^{2^d} \sqrt{s_k p/T}$ .

# Comparison of Estimation Efficiency

- We also considered the Sum of Nuclear (SN) norm (Gandy et al., 2011):

$$\|\mathcal{A}\|_{\text{SN}} = \sum_{i=1}^{2d} \|\mathcal{A}_{(i)}\|_*,$$

$$\hat{\mathcal{A}}_{\text{SN}} = \arg \min_{\mathcal{A}} \left\{ \frac{1}{T} \sum_{t=1}^T \|\mathbf{y}_t - \langle \mathcal{A}, \mathbf{y}_{t-1} \rangle\|_F^2 + \lambda_{\text{SN}} \|\mathcal{A}\|_{\text{SN}} \right\},$$

This is based on the **one-mode matricizations**.

- The square matricization leads to greater estimation efficiency:

Regularizer	Matricization	Estimation error rate
SN	one-mode	$d^{-1} \sum_{i=1}^d \sqrt{r \mathbf{p}_{-i} p / T}$
SSN	square	$2^{-d} \sum_{k=1}^{2^d} \sqrt{s_k p / T}$

- $p = \prod_{i=1}^d p_i$ ,  $\mathbf{p}_{-i} = \prod_{j=1, j \neq i}^d p_j$
- $\sqrt{r} = (2d)^{-1} \sum_{i=1}^{2d} \sqrt{2r_i}$ ,  $r_i = \text{rank}(\mathcal{A}_{(i)}^*)$ , and  $s_k = \text{rank}(\mathcal{A}_{[I_k]}^*)$  are fixed if  $(r_1, \dots, r_{2d})$  are fixed.



# Rank Selection

- The optimization is convex yet the regularizer involves multiple nuclear norms. We propose an ADMM algorithm.
- $\hat{\mathcal{A}}_{\text{SSN}}$  does not guarantee consistent estimation of the ranks. To this end, we further apply a truncation method:
  - Truncated SVD for each  $(\hat{\mathcal{A}}_{\text{SSN}})_{(i)}$ : Retain only singular values exceeding a well-chosen threshold  $\gamma > 0$ . Obtain the truncated factor matrices,  $\tilde{U}_i$ ,  $1 \leq i \leq 2d$ .
  - The truncated core tensor is  $\tilde{\mathcal{G}} = \hat{\mathcal{A}}_{\text{SSN}} \times_{i=1}^{2d} \tilde{U}_i^\top$ .

The truncated SSN (TSSN) estimator is

$$\hat{\mathcal{A}}_{\text{TSSN}} = \tilde{\mathcal{G}} \times_{i=1}^{2d} \tilde{U}_i.$$

- The rank selection is consistent if  $\sqrt{s^*p/T} \ll \gamma \lesssim \min_{1 \leq i \leq 2d} \sigma_{r_i}(\mathcal{A}_{(i)})$ .
- $\hat{\mathcal{A}}_{\text{TSSN}}$  achieves the same asymptotic error rate as  $\hat{\mathcal{A}}_{\text{SSN}}$ .

# Portfolio Returns Forecasting

- Monthly market-adjusted portfolio return series from July 1963 to Dec. 2019.  
[http://mba.tuck.dartmouth.edu/pages/faculty/ken.french/data\\_library.html](http://mba.tuck.dartmouth.edu/pages/faculty/ken.french/data_library.html)
- The portfolios are constructed as the intersections of different levels of
  - size: small and big
  - book-to-market (B/M) ratio: from lowest to highest
  - operating profitability (OP): from lowest to highest
  - Investment (Inv): from lowest to highest
- The first dataset:  $4 \times 4 \times 2$  portfolios formed by OP, B/M ratio, and size.
- The second dataset:  $4 \times 4 \times 2$  portfolios formed by Inv, B/M ratio, and size.

# Models for $4 \times 4 \times 2$ time series

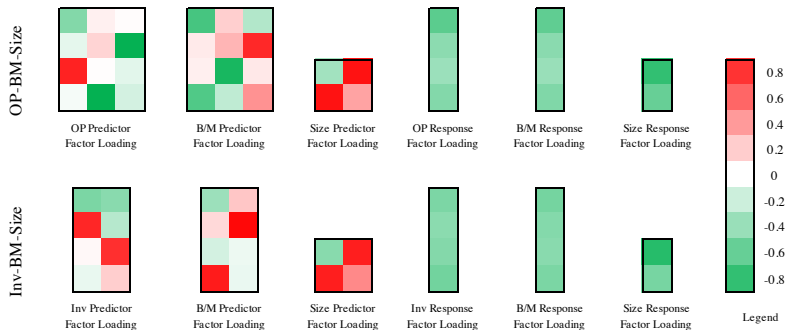
- Vector autoregression (VAR):  $\mathbf{y}_t = \mathbf{A}\mathbf{y}_{t-1} + \mathbf{e}_t$ , where  $\mathbf{A} \in \mathbb{R}^{32 \times 32}$ .
- Vector factor model (VFM):  $\mathbf{y}_t = \mathbf{\Lambda}\mathbf{f}_t + \mathbf{e}_t$ , where  $\mathbf{f}_t$  is the low-dimensional vector-valued latent factor, and  $\mathbf{\Lambda}$  is the loading matrix.
- Multilinear tensor autoregression (MTAR):  $\mathcal{Y}_t = \mathcal{Y}_{t-1} \times_{i=1}^3 \mathbf{B}_i + \mathcal{E}_t$ , where  $\mathbf{B}_1, \mathbf{B}_2 \in \mathbb{R}^{4 \times 4}$  and  $\mathbf{B}_3 \in \mathbb{R}^{2 \times 2}$  are coefficient matrices.
- Tensor factor model (TFM):  $\mathcal{Y}_t = \mathcal{F}_t \times_{i=1}^3 \mathbf{U}_i + \mathcal{E}_t$ , where  $\mathcal{F}_t$  is the low-dimensional tensor-valued latent factor, and  $\mathbf{U}_i$ 's are the loading matrices; see Chen et al. (2022). For prediction, the estimated factors  $\hat{\mathcal{F}}_t$  are then fitted by a VAR(1) model.
- Proposed LRTAR:  $\mathcal{Y}_t = \langle \mathcal{A}, \mathcal{Y}_{t-1} \rangle + \mathcal{E}_t$ , with  $\mathcal{A} = \mathcal{G} \times_{i=1}^6 \mathbf{U}_i$ .

# Results for $4 \times 4 \times 2$ time series

Model		VAR	VFM	MTAR	TFM	LRTAR SSN   TSSN		Best	Worst
OP-BM-Size $4 \times 4 \times 2$ series									
In-sample	$\ell_2$ norm	<b>19.53</b>	20.08	19.89	20.09	19.69	19.70	VAR	TFM
	$\ell_0$ norm	<b>7.67</b>	7.91	7.85	7.92	7.76	7.77	VAR	TFM
Out-of-sample	$\ell_2$ norm	22.27	20.17	20.50	20.11	20.32	<b>19.95</b>	TSSN	VAR
	$\ell_\infty$ norm	10.38	10.04	9.86	10.03	<b>9.29</b>	9.35	SSN	VAR
Inv-BM-Size $4 \times 4 \times 2$ series									
In-sample	$\ell_2$ norm	<b>16.80</b>	17.10	17.05	17.11	16.86	16.88	VAR	TFM
	$\ell_0$ norm	<b>6.25</b>	6.40	6.38	6.41	6.31	6.32	VAR	TFM
Out-of-sample	$\ell_2$ norm	18.70	17.70	16.89	17.67	<b>16.11</b>	16.29	SSN	VAR
	$\ell_\infty$ norm	7.42	7.37	6.79	7.33	6.62	<b>6.43</b>	TSSN	VAR

**Table 1:** Average in-sample forecasting error and out-of-sample rolling forecasting error for  $4 \times 4 \times 2$  tensor-valued portfolio return series. The best cases are marked in **bold**.

# Results for $4 \times 4 \times 2$ time series



**Figure 4:** TSSN estimates of predictor and response factor matrices for  $4 \times 4 \times 2$  tensor-valued portfolio return series. From left to right:  $\tilde{U}_1, \tilde{U}_2, \tilde{U}_3, \tilde{U}_4, \tilde{U}_5$  and  $\tilde{U}_6$ .

## Conclusion

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# Conclusion

- In both topics, we leveraged the tensor decomposition for dimensionality reduction of high-dimensional time series models.
- Besides achieving greater estimation efficiency and forecast accuracy, the resulting models admit interpretable dynamic factor structures that enable the extraction of meaningful insights from massive data.
- In topic 1, we developed a new high-dimensional vector autoregressive model - the Multilinear Low-Rank VAR, and further considered imposing sparsity on the factor matrices for automatic variable selection in factor loadings.
- In topic 2, we developed a novel high-dimensional tensor autoregressive model - the Low-Rank TAR, which is one of the first endeavors of statistical modeling for tensor-valued time series data.

# Thank you!

## References

### Topic 1:

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